

# RCPC: A Sound Causal Discovery Algorithm under Orientation Unfaithfulness

Kenneth Lee, Murat Kocaoglu

Elmore Family School of Electrical and Computer Engineering, Purdue University



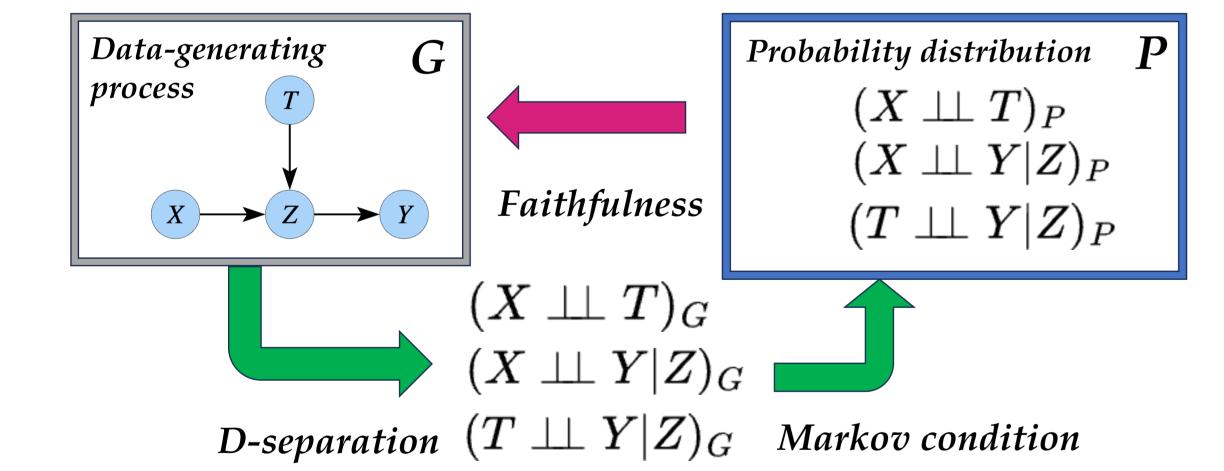
Constraint-based causal discovery approaches often rely on a strong assumption known as faithfulness. A conservative PC (CPC) that relies on a weaker assumption called adjacency faithfulness has been proposed. CPC is conjectured to be complete. We show that the CPC algorithm is not complete and propose two additional sound orientation rules.

#### Probabilistic Causal Inference Fundamentals

- Pearlian framework [Pearl' 09]: Directed acyclic graphs (DAGs) encode causal relation between variables.
- Arrows: Deterministic functional relations called structural equations.

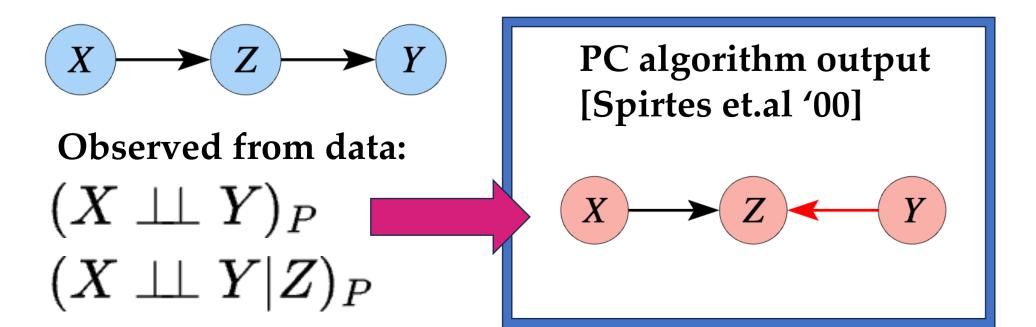
$$X_i = f(Pa_{X_i}, E_{X_i})$$
 ,  $E_i \perp \!\! \perp \!\! \perp E_j$ 

- D-separation
  - In a DAG, a path p between vertices X and Y is **active** (d-connecting) relative to a set of vertices Z if
    - Every non-collider on p is not a member of Z
    - Every collider on p is an ancestor of some members
- D-separation and Conditional Independence

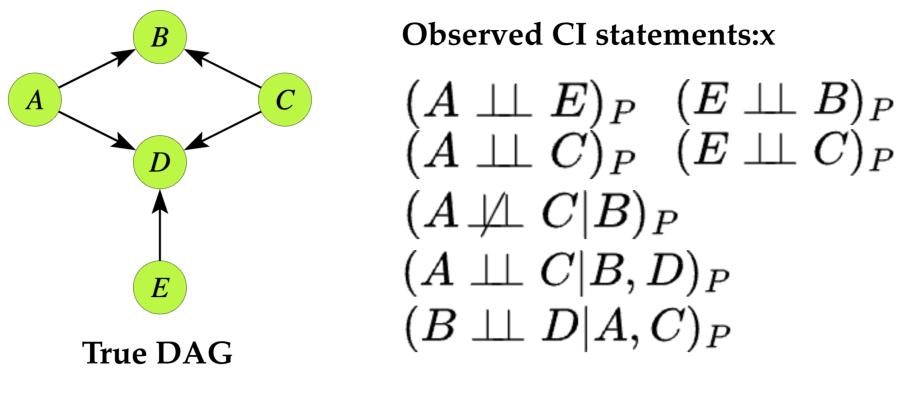


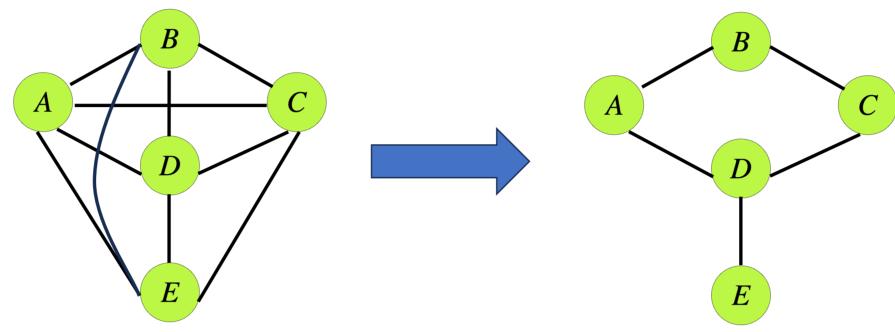
- Adjacency faithfulness
  - If X and Y are adjacent in G, they are conditionally dependent given any subsets of V.
- Orientation faithfulness
  - Let  $\langle X, Y, Z \rangle$  be any unshielded triple in G.
    - If  $X \to Y \leftarrow Z$ , then X and Z are dependent given any subset that contains Y;
    - Otherwise, X and Z are dependent conditional on any subset that does not contain Y

Example (Adj. faithfulness holds with orientation unfaithfulness)



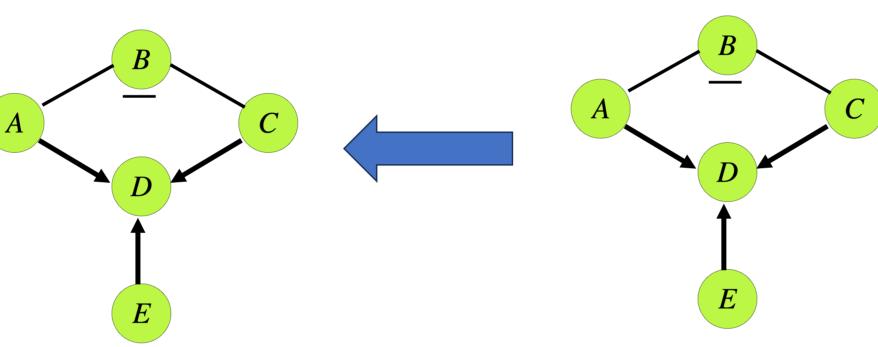
#### CPC Algorithm [Ramsey et. al'12]





**Step 1:** Start from a complete graph

**Step 2:** Remove edges based on conditional independence



**Step 4:** Apply Meek rules to unshielded non-colliders, not including triples that are marked unfaithful

Step 3: For each unshielded triple  $\langle X, Y, Z \rangle$ , • if Y is not in any separating set,

- orient  $X \rightarrow Y \leftarrow Z$ . • If Y is in all separating sets, orient X - Y - Z.
- Otherwise, mark  $X \underline{Y} Z$

## CPC Is Not Complete

A critical observation for the example above:

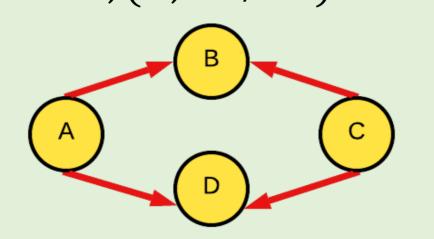
- By Markov condition,  $(A \not\perp \!\!\! \perp C|B)_P$  implies the triple  $\langle A, B, C \rangle$  cannot be a non-collider.
- Hence,  $\langle A, B, C \rangle$  should be oriented as  $A \to B \leftarrow C$ .

#### Sources of Unfaithfulness

**Cancelled Paths:** in a DAG G=(V, E) with any unfaithful distribution p compatible with G, we say the active paths q between a set of variables **X** and another set of variables **Y** are cancelled relative to a set of vertices  $Z \subseteq V$ ,  $(X, Y \not\subseteq Z)$  if

 $(\mathbf{X} \not\perp \!\!\!\! \perp \mathbf{Y} | \mathbf{Z})_G$  and





When all cancelled paths from A to C relative to B are along all the d-connecting paths from X to Y relative to J, we denote it as  $Path(A, C, B) \subseteq_C Path(X, Y, J)$ 

### Revised CPC (RCPC) Algorithm

Following step 4 of CPC, we recursively apply R5 and R6 until there is no more edges that can be oriented by them. Let G be the resulting graph after step 4.

**R5**: For every unshielded triple  $\langle A, B, C \rangle$  that has been marked unfaithful,

- a) if  $A \to B \leftarrow C$ , unmark  $A \to B \leftarrow C$  as  $A \to B \leftarrow C$ .
- I. Mark all CIs  $(A \perp \!\!\!\perp C|W)_P$  as NM (non-Markov) statement for any W that contains B and
- II. If  $Path(A, C, B) \subseteq_C Path(X, Y, J)$ , mark  $(X \perp \!\!\! \perp Y | J)_P$  as NM statement for any J that contains B
- b) else, mark  $(A \perp \!\!\! \perp C|S)_P$  as NM statement for any S that does not contain B and unmark the triple.
- I. If  $Path(A, C, \emptyset) \subseteq_C Path(X, Y, D)$ ,  $mark(X \perp \!\!\!\perp Y|D)_P$  as NM statement for any D that does not contain B.

Then, excluding all NM statements, for each unshielded triple  $\langle A, T, C \rangle$  that is marked as unfaithful:

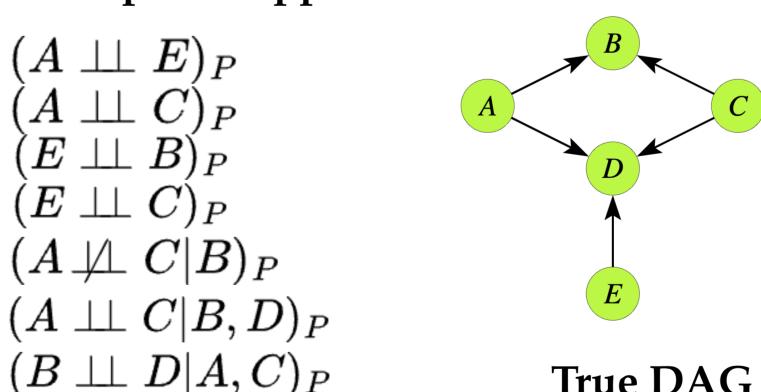
- If T is not in any set conditional on which A and C are independent, orient  $A \underline{T} C$  as  $A \rightarrow$  $\underline{\mathsf{T}} \leftarrow \mathcal{C}$ .
- If T is in all such sets conditional on which A and C are independent, unmark  $\langle A, T, C \rangle$ .

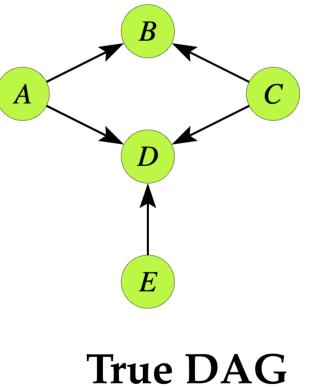
**R6:** Recursively apply R1, R3, and R4 of Meek rules [Meek'95] to unshielded non-colliders that are not marked as unfaithful except that R2 can be applied to any triple.

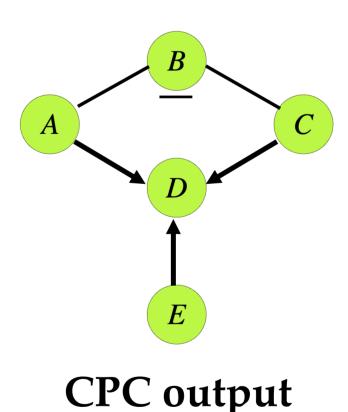
• **Additionally,** for any unshielded triple  $\langle A, T, C \rangle$  that is oriented as as  $A \to \underline{T} - C$ , if there is an undirected path p e.g.  $Q - \cdots - C$  and no triples along p has been marked unfaithful and there is a directed path q e.g.  $Q \rightarrow \cdots \rightarrow A$ . Then, we orient  $A \rightarrow \underline{T} \leftarrow C$  (keeping the underline for marking NM statement).

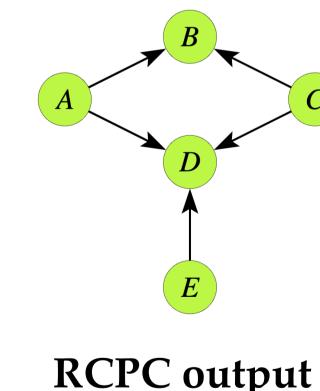
Theorem: Under the causal Markov and Adjacency-Faithfulness assumptions, the RCPC algorithm is correct in the sense that given a perfect conditional independence oracle, the algorithm returns an extended pattern that represents the true causal DAG.

## Example 1 (Application of R5):



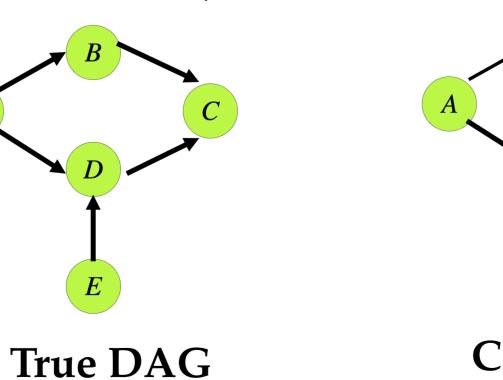






Example 2 (Application of R5 and R6):

 $(B \perp \perp D|A,C)_P$  $(A \perp \perp C|B,D)_P$ 



**CPC** output

RCPC output

**R5:** unmark  $\langle A, B, C \rangle$ .

 $(A \perp \!\!\!\perp C)_P$ 

 $(A \downarrow \!\!\! \perp C|B)_P$ 

 $(A \perp \downarrow C | D)_P$ 

**R6:** orient  $\langle B, C, D \rangle$  as an unshielded collider

#### Reference

J. Pearl, Causality: Models, Reasoning and Inference. Cambridge University Press, 2009 Spirtes, Peter, Clark Glymour, and Richard Scheines. Causation, prediction, and search. MIT press, 2001. Ramsey, Joseph, Peter Spirtes, and Jiji Zhang. "Adjacency-faithfulness and conservative causal inference." Proceedings of the Twenty-Second Conference on Uncertainty in Artificial Intelligence. 2006. Meek, Christopher. "Causal inference and causal explanation with background knowledge." Proceedings of the Eleventh conference on Uncertainty in artificial intelligence. 1995.